

BROWN

Adversarial Multiclass Learning under Weak Supervision with Performance Guarantees

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AMCL - A First Look

Adversarial MultiClass Learning

- Semi-supervised framework for **multiclass learning** from **weak labelers**

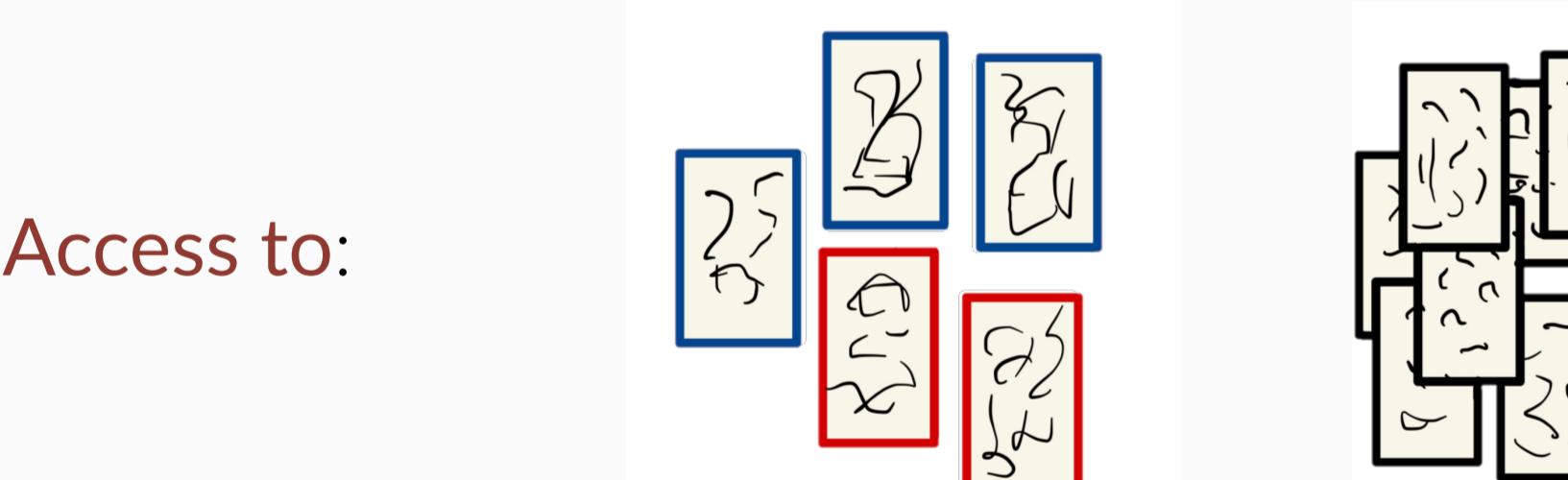
- Adversarial feasible labeling** of unlabeled data during training
 - Feasibility: use labeled data to compute statistical constraints on weak labelers

Contribution 1st semi-supervised learner for *arbitrarily correlated* weak labelers with:

- optimization convergence guarantees for the adversarial multiclass learning
- generalization bound for the learned model

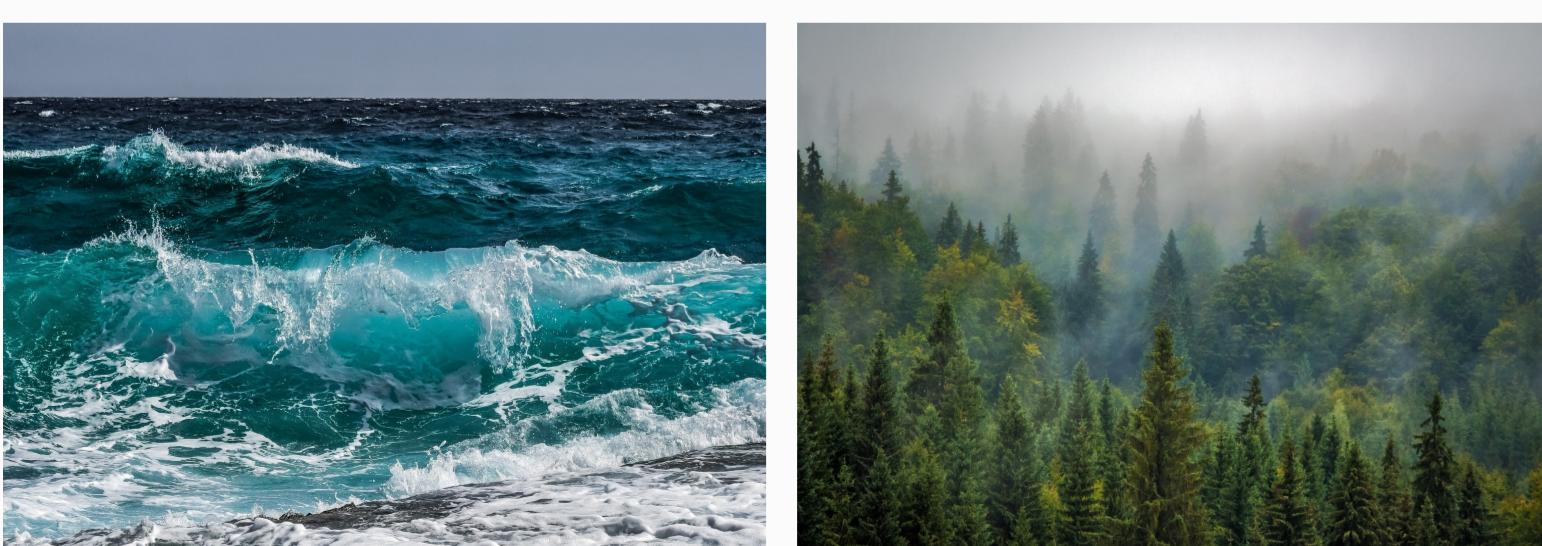
The Problem Setting

Classification task: distribution \mathcal{D} over $\mathcal{X} \times \mathcal{Y}$

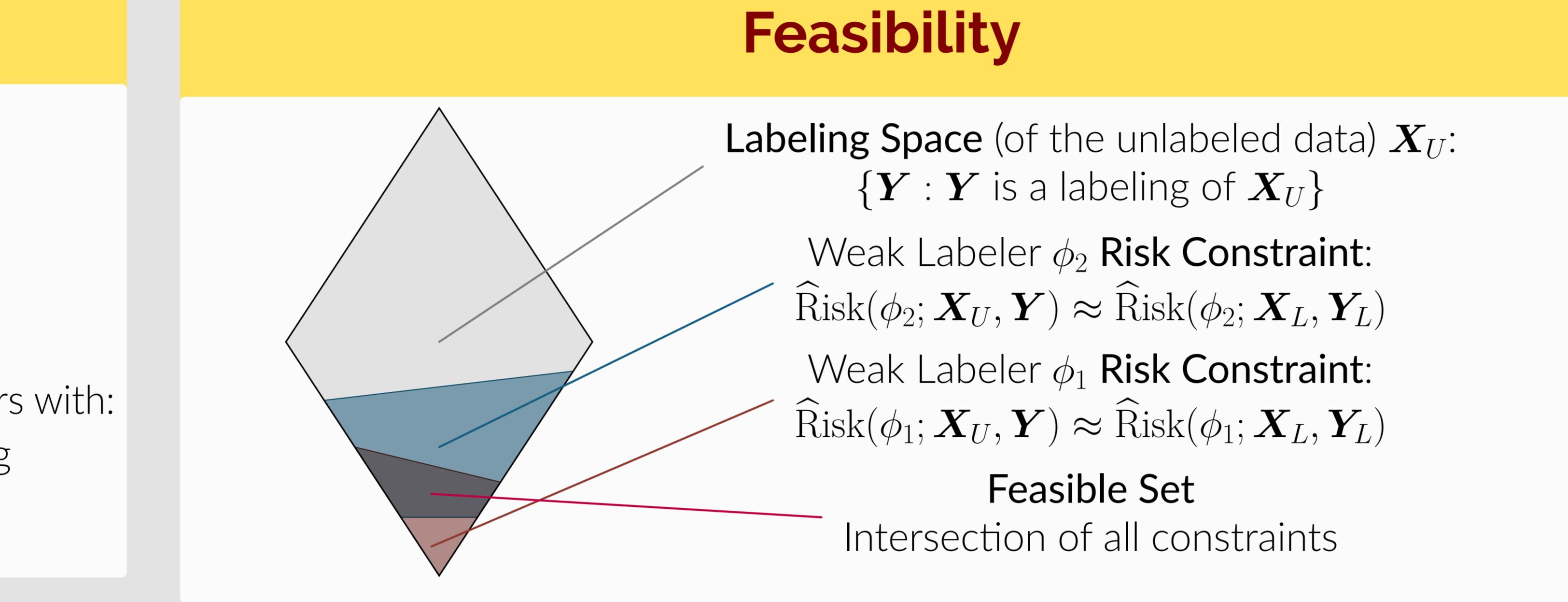


ϕ_1, \dots, ϕ_n

Weak labelers: classifiers for mildly related task



Images made by Those Icons (wheel, siren), fjsfotio (ambulance), Freepik (truck) from flaticon.com



The Optimization Objective

Adversarial setting \Rightarrow Minimax Objective

- Empirical risk of a model θ computed w.r.t. **adversarial feasible labeling**

$$\min_{\theta \in \Theta} \underbrace{\max_{\text{feasible } \mathbf{Y}} \widehat{\text{Risk}}(h_\theta; \mathbf{X}_U, \mathbf{Y})}_{\text{Subgradient Steps}}$$

- \mathbf{Y} is soft-labels: we use expected loss over label distributions
 \Rightarrow empirical risk is linear w.r.t. \mathbf{Y}

Optimization Guarantees

If the loss is **convex** and L -**Lipschitz Continuous** w.r.t. θ , and we run $T = \Omega(L^2/\varepsilon^2)$ iterations of the subgradient method using step size $\alpha = \varepsilon/L^2$:

$$\max_{\text{feasible } \mathbf{Y}} \widehat{\text{Risk}}(h_\theta; \mathbf{X}_U, \mathbf{Y}) \leq \min_{\theta} \max_{\text{feasible } \mathbf{Y}} \widehat{\text{Risk}}(h_\theta; \mathbf{X}_U, \mathbf{Y}) + \varepsilon$$

Generalization Bound

$$\hat{\theta} = \arg \min_{\theta \in \Theta} \max_{\text{feasible } \mathbf{Y}} \widehat{\text{Risk}}(h_\theta; \mathbf{X}_U, \mathbf{Y}) \text{ vs } \theta^* = \arg \min_{\theta \in \Theta} \text{Risk}(h_\theta)$$

If loss codomain is $[0, B]$, then w.h.p., true labeling is feasible, and

$$\underbrace{\text{Risk}(h_\theta) - \text{Risk}(h_{\theta^*})}_{\text{Optimality Gap}} \leq \underbrace{B \cdot D_f}_{\text{Adversarial Error}} + \underbrace{\sup_{\text{feasible } \mathbf{Y}} 4\widehat{\mathbf{R}}_{m_U}(\mathcal{L}; \mathbf{X}_U, \mathbf{Y})}_{\text{Uniform Convergence Bound}} + O\left(B\sqrt{\frac{\ln \frac{1}{\delta}}{m_U}}\right) \underbrace{\text{Tail Bound}}$$

Average diameter of the feasible set

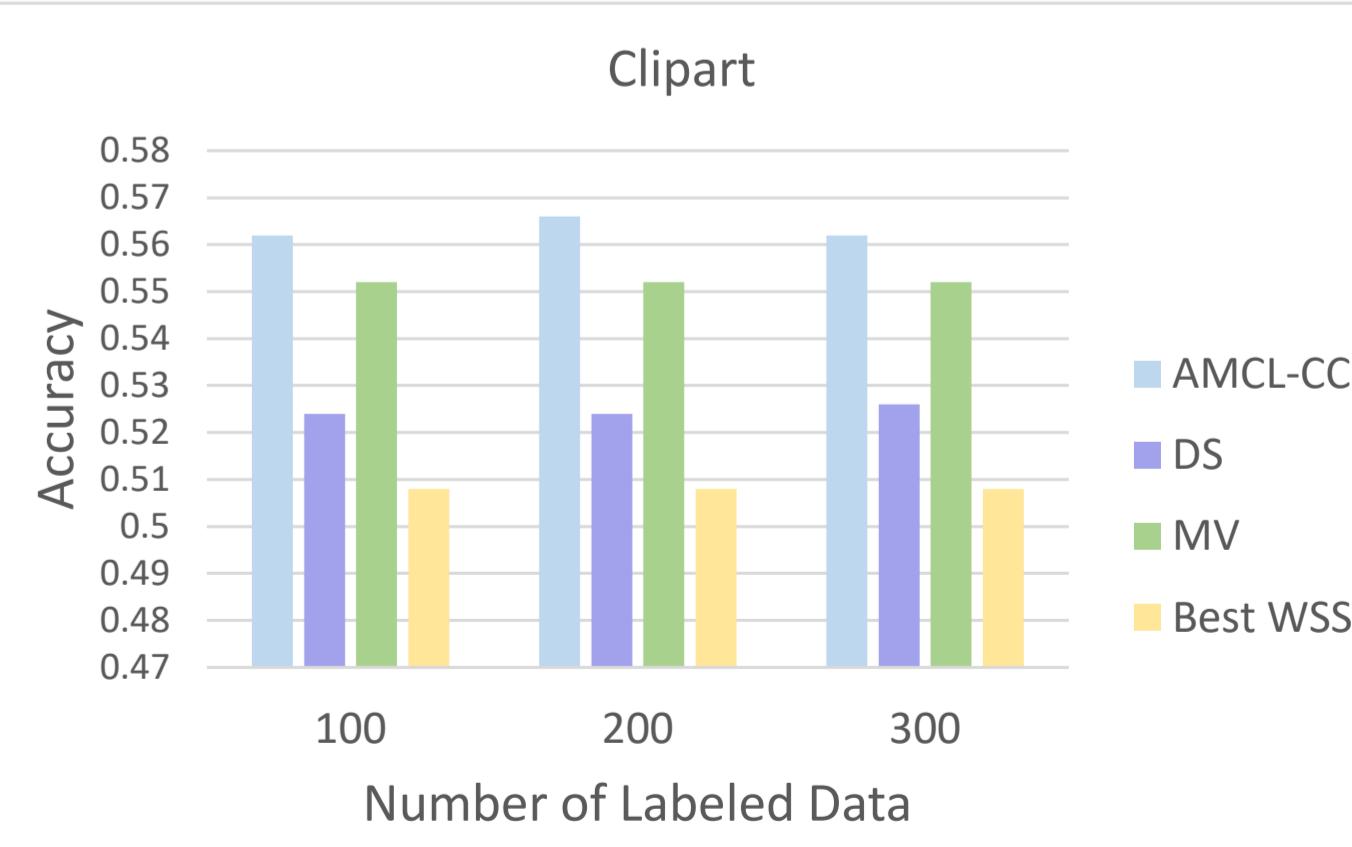
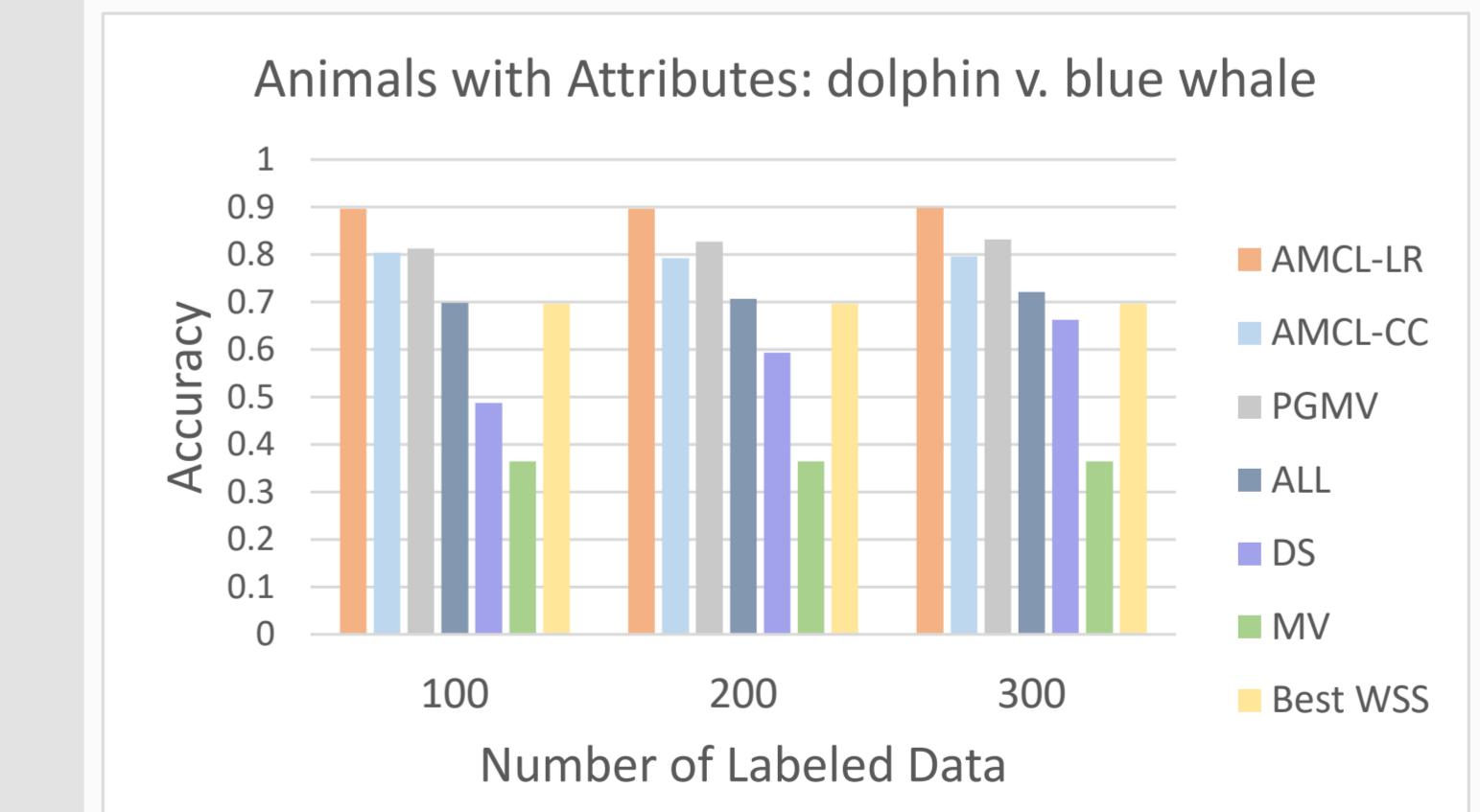
Geometrically quantifies weak labeler information

$$D_f = \frac{1}{m_U} \sup_{\mathbf{Y}, \mathbf{Y}''} \sum_{j=1}^{m_U} \|\mathbf{y}'_j - \mathbf{y}''_j\|_1$$

Experiments

We run experiments over two *image* datasets

- Animals with Attributes (binary)
- DomainNet (multiclass)
- We use two practical instantiations of our general framework:
 - AMCL-CC: convex combination of the output of the weak labelers
 - AMCL-LR: logistic regression (softMax) over images' features



Our method often outperforms the **baselines**, and **state-of-the-art** algorithms:

- MV** (Majority Vote), **DS** (Dawid-Skene), **Best WSS** (Best weak labeler)
- ALL** (Adversarial Label Learning), **PGMV** (Performance-Guaranteed Majority Vote)